

The 475 gyro is an all-welded, hermetic construction, capable of meeting performance requirements in extreme operating environments of vibration, shock, altitude, humidity and temperature. The heart of the gyro consists of a synchronous hysteresis motor whose high reliability is enhanced by preloaded inertial grade ball bearings and advanced lubricants. The spin motor assembly is dynamically balanced using state-of-the-art high precision balancing equipment and then run-in for a minimum of 96 hours to fully channel the lubricants. The gimbal is supported by a specially designed torsion wire that yields very low hysteresis with

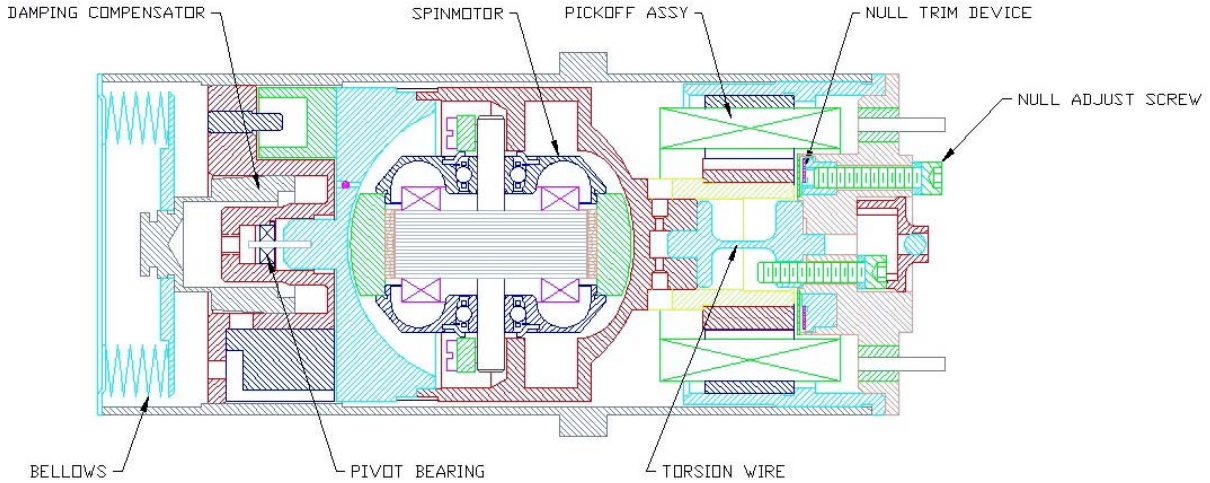


excellent repeatability and a miniature high precision ball bearing enabling high g forces without distortion. The angular position of the gimbal is detected by a variable reluctance pickoff which contains quadrature and null trimming capabilities. Utilizing state of the art materials for the stator and rotor stacks, it provides high sensitivity, excellent linearity and low noise. A stable and inert silicone-based fluid is used for gimbal neutral buoyancy and damping. It's characteristics allow gyro start-up at low temperatures of -54 deg C. Dynamic characteristics of the gyro are maintained throughout the temperature range by means of a bellows-operated, variable-orifice, damping compensator. The compensator is a mechanical device and requires no power source. An external null trimming device enables mechanical trimming of the pickoff without electrical components that would effect pickoff phase shift. All gyros are temperature cycled from -65 deg F to +240 deg F for 48 hours to stress relieve all components and assure maximum drift stability.

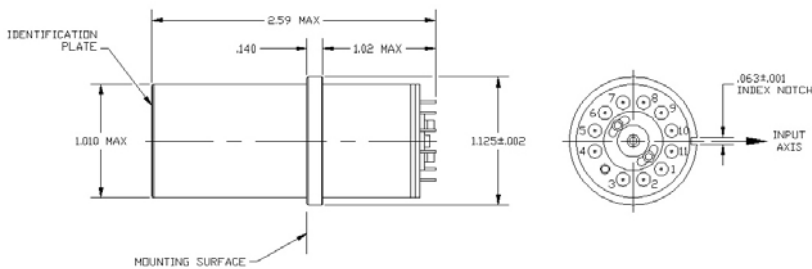
475 Series Applications

| Program | Application | Comments |
|------------------|---------------|------------------------------|
| Phalanx | Weapon System | Radar Stabilization |
| F-15 | Aircraft | Radar Rate Stabilization |
| F-16 | Aircraft | Heads Up Display Rate Sensor |
| Standard Missile | Missile | Autopilot |
| AN/APQ-150A | Aircraft | Tracking Radar |
| SATCOM | Shipboard | Antenna Stabilization |
| AN/APQ-150 | Aircraft | Radar System |
| AN/ASQ-173 | Aircraft | Laser Tracker |
| F-16 | Aircraft | Flight Control |
| LANTIRN | Aircraft | Target Pod |
| F-4 | Aircraft | |

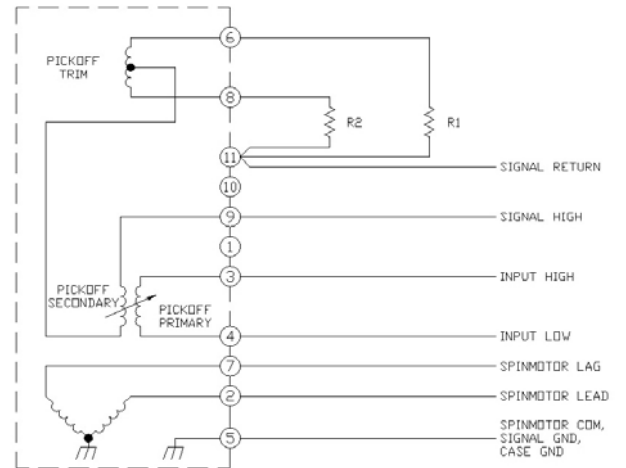
Form, Fit and Function replacements for Honeywell GG445,
BAE GI-G5 and GR-G5 Series



Typical 475 Gyro Assembly



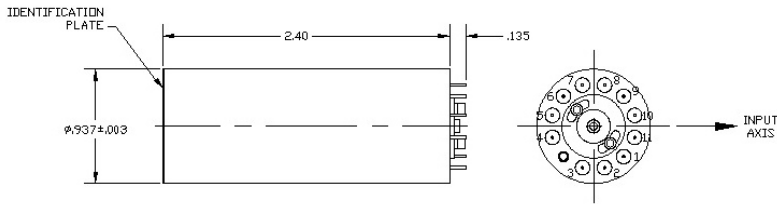
475 Gyro Outline - 1.00 Diameter



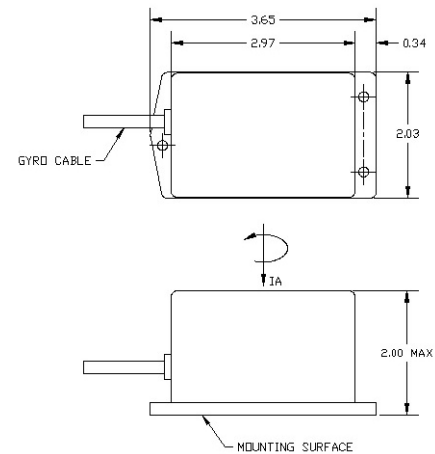
Typical 475 Gyro Wiring Diagram

See Notes on next page

Form, Fit and Function replacements for Honeywell GG445,
BAE GI-G5 and GR-G5 Series



475 Gyro Assembly - 0.94 Diameter



475 Gyro Outline with Electronics

(Shown is a typical Humphrey / Goodrich RG78 Outline)

The Outline and Wiring Diagrams should be only used as a guide. The 475 series of rate gyroscopes can be configured to customer specifications. Some of the options are listed below:

- Spin motor available with common leg of 2 phase motor grounded or as a separate return.
- Self test torquer.
- Cables, connectors, mounting flanges and brackets, magnetic shielding and long life spin bearings.
- Various combinations of gyro inputs and outputs:
 - AC input - AC output
 - AC input - DC output
 - DC input - DC output
- Spin motor and Pickoff drive electronics.
- Operational bit output.

USD can also package multiple gyros with all the necessary electronics for multi-axis sensing. For more information, please call Sales at (631) 842-5600 or send an email to sales@usdynamicscorp.com.



Rate Gyroscopes 475 Series

| USD Part Number | | 475134 | 475150 | 475163 | 475194 | 475195 |
|------------------------------|---------------|---------------|---------------|---------------|---------------|---------------|
| NSN | | 6615010714292 | 6615012205377 | 6615014326690 | 6615013102233 | 6615013399457 |
| Honeywell Part Number | | 10059849 | | | 10134100-101 | |
| BAE Part Number | | | 304545 | 64667-302 | | 67619-306 |
| PARAMETER | UNIT | | | | | |
| Rate | ± deg/sec | 90 | 150 | 300 | 20 | 60 |
| SPINMOTOR: | | | | | | |
| Voltage (2 phase) | volts rms | 26 | 14.5 | 7 | 26 | 26 |
| Frequency | Hz | 800 | 800 | 900 | 400 | 400 |
| Current - Start/phase | amps rms max | | | 0.6 | | |
| - Run/phase | amps rms max | 0.192 | 0.36 | 0.4 | | |
| Power (Total) - Start | watts max | | | | 5 | 6 |
| - Run | watts max | | | | 4 | 5 |
| Run-Up Time | sec max | 45 | 5 | 60 | 30 | 25 |
| PICKOFF: | | | | | | |
| Voltage | volts rms | 26 | 15 | 20 | 26 | 26 |
| Frequency | Hz | 800 | 800 | 4000 | 400 | 400 |
| Load | ohms, Pf max | | | | 10 K | |
| Scale Factor | mv/deg/sec | 75 | 35 | 20 | 85 | 100 |
| GYRO PERFORMANCE: | | | | | | |
| Threshold | deg/sec | 0.01 | 0.01 | | 0.01 | 0.015 |
| Linearity | % max | | 2 | 1 | | 1 |
| Natural Frequency | Hz min | 22 | 42 | 60 | 25 | 28 |
| Damping Ratio | ----- | 0.7 to 2.0 | 0.4 to 0.8 | 0.35 to 1.3 | 0.7 ± 0.3 | 0.4 to 1.0 |
| Acceleration Sensitivity | deg/sec/g max | 0.05 | 0.06 | 0.1 | 0.1 | 0.1 |
| Hysteresis | deg/sec max | 0.1 | 0.15 | 0.1% of input | 0.03 | 0.1 |
| Zero Offset | deg/sec max | 0.4 max | 0.11 | 0.3 | 0.1 | 0.1 |
| ENVIRONMENTS: | | | | | | |
| Operating Temp. | °F | -40 to +185 | 140 ± 5 Htd | -65 to +203 | -65 to +150 | -40 to +160 |
| Shock, Duration | g-peak,msec | 15, 11 | 40, 11 | 80, 11 | 20, 9 | |
| Vibration 20-2000 Hz | g-peak | 10g's sine | 10g's random | 15g's sine | 20g's sine | |
| Acceleration | g | 10 | 40 | 18 | | |



Rate Gyroscopes 475 Series

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|------------------------------|---------------|-------------|---------------|---------------|-------------|------------|
| USD Part Number | | 475196 | 475197 | 475198 | 475199 | 475200 |
| NSN | | | 6615013533294 | 6615004070166 | | |
| Honeywell Part Number | | | S101280 | | | |
| BAE Part Number | | 103162 | 79199-333 | 79148-302 | 67696-301 | 64625-302 |
| PARAMETER | UNIT | | | | | |
| Rate | ± deg/sec | 50 | 100 | 30 | 30 | 40 |
| SPINMOTOR: | | | | | | |
| Voltage (2 phase) | volts rms | 26 | 26 | 26 | 26 | 26 |
| Frequency | Hz | 800 | 400 | 400 | 800 | 400 |
| Current - Start/phase | amps rms max | | 125 | | | |
| - Run/phase | amps rms max | | 100 | | | |
| Power (Total) - Start | watts max | 5.5 | | 4.5 | 3.5 | 4 |
| - Run | watts max | 4.5 | | 4.5 | 2.5 | 2.5 |
| Run-Up Time | sec max | 25 | 30 | 30 | 30 | 25 |
| PICKOFF: | | | | | | |
| Voltage | volts rms | 26 | 26 | 26 | 26 | 26 |
| Frequency | Hz | 800 | 400 | 400 | 800 | 400 |
| Load | ohms, Pf max | | | 10K | 10K | 100K |
| Scale Factor | mv/deg/sec | 93 | 110 | 140 | 100 | 134 |
| GYRO PERFORMANCE: | | | | | | |
| Threshold | deg/sec | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 |
| Linearity | % max | 1 | 2 | 1 | 1 | 2 |
| Natural Frequency | Hz min | 28 | 35 | 25 | 25 | 19 |
| Damping Ratio | ----- | 0.4 to 0.8 | 0.5 to 0.9 | 0.5 to 2.4 | 0.7 to 1.3 | 0.3 to 0.7 |
| Acceleration Sensitivity | deg/sec/g max | 0.05 | 0.05 | 0.08 | 0.05 | 0.1 |
| Hysteresis | deg/sec max | 0.05 | 0.1 | 0.3 | 0.03 | 0.04 |
| Zero Offset | deg/sec max | 0.1 | 0.1 | 0.15 | 0.1 | 0.3 |
| ENVIRONMENTS: | | | | | | |
| Operating Temp. | °F | -25 to +120 | -20 to +160 | -65 to +212 | +14 to +160 | +60 to +90 |
| Shock, Duration | g-peak,msec | 20 | 300, 7 | 25, 11 | 50, 11 | 50, 11 |
| Vibration 20-2000 Hz | g-peak | | 2 | 5 | 12 | 5 |
| Acceleration | g | | | 6 | 15 | 10 |



Rate Gyroscopes 475 Series

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|------------------------------|---------------|---------------|---------------|-------------|------------|-------------|
| USD Part Number | | 475201 | 475202 | 475203 | 475204 | 475205 |
| NSN | | 6615010477463 | 6615010683593 | | | |
| Honeywell Part Number | | | | | | |
| BAE Part Number | | 67561-302 | 64654-301 | 64670-301 | 67652-301 | 67547-301 |
| PARAMETER | UNIT | | | | | |
| Rate | ± deg/sec | 40 | 50 | 50 | 50 | 60 |
| SPINMOTOR: | | | | | | |
| Voltage (2 phase) | volts rms | 26 | 27 Square | 28 | 28 | 26 |
| Frequency | Hz | 400 | 800 | 400 | 400 | 400 |
| Current - Start/phase | amps rms max | | | | | |
| - Run/phase | amps rms max | | | | | |
| Power (Total) - Start | watts max | 4 | 3.5 | 4.5 | 3.5 | 5 |
| - Run | watts max | 2.5 | 2.5 | 3 | 3 | 4.5 |
| Run-Up Time | sec max | 25 | 25 | 25 | 25 | 60 |
| PICKOFF: | | | | | | |
| Voltage | volts rms | 26 | 27 | 8 | 26 | 26 |
| Frequency | Hz | 400 | 800 | 1970 | 400 | 400 |
| Load | ohms, Pf max | 100K | 10K | 10K | 10K | 10K |
| Scale Factor | mv/deg/sec | 140 | 100 | 150 | 100 | 100 |
| GYRO PERFORMANCE: | | | | | | |
| Threshold | deg/sec | 0.01 | 0.015 | 0.01 | 0.01 | 0.03 |
| Linearity | % max | 2 | 1 | 2 | 2 | 2 |
| Natural Frequency | Hz min | 19 | 28 | 25 | 25 | 31 |
| Damping Ratio | ----- | 0.4 to 0.6 | 0.4 to 1.3 | 0.3 to 1.0 | 0.5 to 1.2 | 0.4 to 2.0 |
| Acceleration Sensitivity | deg/sec/g max | 0.075 | 0.05 | 0.05 | 0.05 | 0.1 |
| Hysteresis | deg/sec max | 0.04 | 0.03 | 0.03 | 0.05 | 0.06 |
| Zero Offset | deg/sec max | 0.07 | 0.1 | 0.05 | 0.1 | 0.3 |
| ENVIRONMENTS: | | | | | | |
| Operating Temp. | °F | +60 to +90 | -55 to +160 | -65 to +160 | 0 to +180 | -25 to +125 |
| Shock, Duration | g-peak,msec | 50, 11 | 40, 11 | 50, 11 | 50, 11 | 400, 0.5 |
| Vibration 20-2000 Hz | g-peak | 5 | 10 | 5 | 9 | 2.5 |
| Acceleration | g | 10 | 20 | 10 | 10 | 20 |



Rate Gyroscopes 475 Series

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|------------------------------|---------------|------------|------------|-------------|-------------|-------------|
| USD Part Number | | 475206 | 475207 | 475208 | 475209 | 475210 |
| NSN | | | | | | |
| Honeywell Part Number | | | | | | |
| BAE Part Number | | 67597-301 | 67513-303 | 64543-301 | 67513-301 | 67708 |
| PARAMETER | UNIT | | | | | |
| Rate | ± deg/sec | 90 | 100 | 100 | 100 | 100 |
| SPINMOTOR: | | | | | | |
| Voltage (2 phase) | volts rms | 26 | 30 Square | 20.5 Square | 30 Square | 28 |
| Frequency | Hz | 400 | 400 | 480 | 400 | 800 |
| Current - Start/phase | amps rms max | | | | | |
| - Run/phase | amps rms max | | | | | |
| Power (Total) - Start | watts max | 5 | 8 | 3 | 8 | 4 |
| - Run | watts max | 4 | 5 | 2.25 | 5 | 3.5 |
| Run-Up Time | sec max | 20 | 5 | 30 | 5 | 20 |
| PICKOFF: | | | | | | |
| Voltage | volts rms | 26 | 10 | 8 | 10 | 28 |
| Frequency | Hz | 2600 | 4800 | 2404 | 4800 | 800 |
| Load | ohms, Pf max | 10K | 90K | 62K | 90K | 30K |
| Scale Factor | mv/deg/sec | 41 | 50 | 100 | 50 | 160 |
| GYRO PERFORMANCE: | | | | | | |
| Threshold | deg/sec | 0.01 | 0.04 | 0.02 | 0.04 | 0.01 |
| Linearity | % max | 2 | 1 | 1 | 1 | 2 |
| Natural Frequency | Hz min | 33 | 60 | 60 | 60 | 38 |
| Damping Ratio | ----- | 0.7 to 1.3 | 0.3 to 1.0 | 0.4 to 0.7 | 0.3 to 1.0 | 0.4 to 1.0 |
| Acceleration Sensitivity | deg/sec/g max | 0.1 | 0.3 | 0.04 | 0.3 | 0.06 |
| Hysteresis | deg/sec max | 0.1 | 0.02 | 0.15 | 0.2 | 0.15 |
| Zero Offset | deg/sec max | 0.25 | 1 | 0.4 | 1 | 0.15 |
| ENVIRONMENTS: | | | | | | |
| Operating Temp. | °F | 0 to +140 | 0 to +225 | +30 to +190 | -65 to +225 | +60 to +160 |
| Shock, Duration | g-peak,msec | 50, 11 | 45, 10 | 20, 30 | 45, 10 | 50, 11 |
| Vibration 20-2000 Hz | g-peak | 4 | 12 | 8 | 12 | 12 |
| Acceleration | g | 15 | 30 | 20 | 30 | 17 |



Rate Gyroscopes 475 Series

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|------------------------------|---------------|--------------|-------------|---------------|------------|-------------|
| USD Part Number | | 475211 | 475212 | 475213 | 475214 | 475215 |
| NSN | | | | 6615010682149 | | |
| Honeywell Part Number | | | | | | |
| BAE Part Number | | 67510-301 | 64640-302 | 64654-302 | 67597-302 | 64669-301 |
| PARAMETER | UNIT | | | | | |
| Rate | ± deg/sec | 150 | 100 | 250 | 270 | 300 |
| SPINMOTOR: | | | | | | |
| Voltage (2 phase) | volts rms | 30/15 run sq | 27 Square | 27 Square | 26 | 7 Square |
| Frequency | Hz | 1200 | 400 | 800 | 400 | 900 |
| Current - Start/phase | amps rms max | | | | | |
| - Run/phase | amps rms max | | | | | |
| Power (Total) - Start | watts max | 56 VA | 6.5 | 3.5 | 5 | 4.7 |
| - Run | watts max | 7.5 VA | 4.5 | 2.5 | 4 | 2 |
| Run-Up Time | sec max | 2 | 20 | 25 | 20 | 60 |
| PICKOFF: | | | | | | |
| Voltage | volts rms | 9 | 10 | 27 | 26 | 20 |
| Frequency | Hz | 3125 | 4800 | 800 | 2600 | 4000 |
| Load | ohms, Pf max | 51K | 10K, 500 | 10K | 10K | 15K, 2200 |
| Scale Factor | mv/deg/sec | 10 | 100 | 20 | 14 | 20 |
| GYRO PERFORMANCE: | | | | | | |
| Threshold | deg/sec | 0.015 | 0.01 | 0.05 | 0.01 | 0.01 |
| Linearity | % max | 1.6 | 1 | 1 | 2 | 1 |
| Natural Frequency | Hz min | 58 | 56 | 60 | 43 | 60 |
| Damping Ratio | ----- | 0.5 to 0.8 | 0.4 to 1.0 | 0.3 to 1.0 | 0.7 to 1.3 | 0.4 to 1.5 |
| Acceleration Sensitivity | deg/sec/g max | 0.05 | 0.05 | 0.05 | 0.1 | 0.1 |
| Hysteresis | deg/sec max | 0.2 | 0.2 | 0.15 | 0.2 | 0.3 |
| Zero Offset | deg/sec max | 0.5 | 0.25 | 0.5 | 0.5 | 0.3 |
| ENVIRONMENTS: | | | | | | |
| Operating Temp. | °F | +150 to +185 | -30 to +225 | -55 to +160 | 0 to +120 | -65 to +220 |
| Shock, Duration | g-peak,msec | 86, 1 | 150, 1 | 40, 11 | 50, 11 | 80, 11 |
| Vibration 20-2000 Hz | g-peak | 19 | 15 | 10 | 4 | 10 |
| Acceleration | g | 50 | 18 | 20 | 15 | 18 |



Rate Gyroscopes 475 Series

| USD Part Number | | 475193 | 475216 | 475217 | 475218 | 475219 |
|------------------------------|---------------|-------------|-------------|------------|------------|---------------|
| NSN | | | | | | 6615011611460 |
| Honeywell Part Number | | | | | | |
| BAE Part Number | | 67701-301 | 67705-301 | 79199-301 | 67696-303 | 79172-302 |
| PARAMETER | UNIT | | | | | |
| Rate | ± deg/sec | 300 | 400 | 20 | 30 | 40 |
| SPINMOTOR: | | | | | | |
| Voltage (2 phase) | volts rms | 26 | 26 | 26 | 26 | 26 |
| Frequency | Hz | 800 | 400 | 400 | 800 | 400 |
| Current - Start/phase | amps rms max | | | | | |
| - Run/phase | amps rms max | | | | | |
| Power (Total) - Start | watts max | 4 | 5 | 5 | 5 | 5 |
| - Run | watts max | 3.5 | 4 | 4 | 4 | 4 |
| Run-Up Time | sec max | 60 | 20 | 30 | 20 | 25 |
| PICKOFF: | | | | | | |
| Voltage | volts rms | 26 | 20 | 26 | 26 | 26 |
| Frequency | Hz | 800 | 4000 | 400 | 800 | 400 |
| Load | ohms, Pf max | 20K | 30K | 10K | 10K | 15K |
| Scale Factor | mv/deg/sec | 20 | 7.5 | 250 | 100 | 150 |
| GYRO PERFORMANCE: | | | | | | |
| Threshold | deg/sec | 0.01 | 0.05 | 0.01 | 0.01 | 0.01 |
| Linearity | % max | 1 | 1 | 2 | 1 | 3 |
| Natural Frequency | Hz min | 47 | 80 | 14 | 25 | 17 |
| Damping Ratio | ----- | 0.3 to 1.5 | 0.3 to 1.5 | 0.5 to 0.9 | 0.3 to 1.5 | 0.4 to 0.6 |
| Acceleration Sensitivity | deg/sec/g max | 0.1 | 0.2 | 0.05 | 0.05 | 0.05 |
| Hysteresis | deg/sec max | 0.25 | 0.4 | 0.02 | 0.1 | 0.08 |
| Zero Offset | deg/sec max | 0.75 | 1 | 0.04 | 0.3 | 0.08 |
| ENVIRONMENTS: | | | | | | |
| Operating Temp. | °F | -65 to +160 | -40 to +180 | 0 to +160 | 0 to +160 | +30 to +140 |
| Shock, Duration | g-peak,msec | 25, 11 | 25, 20 | | 50, 11 | |
| Vibration 20-2000 Hz | g-peak | 6 | 9 | | 12 | |
| Acceleration | g | 18 | 45 | | 15 | |



Rate Gyroscopes 475 Series

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|------------------------------|---------------|-------------|-------------|-------------|-------------|-------------|
| USD Part Number | | 475220 | 475221 | 475222 | 475223 | 475224 |
| NSN | | | | | | |
| Honeywell Part Number | | | | | | |
| BAE Part Number | | 67538-301 | 103013-301 | 67618-301 | 67640-303 | 67640-301 |
| PARAMETER | UNIT | | | | | |
| Rate | ± deg/sec | 40 | 40 | 60 | 60 | 60 |
| SPINMOTOR: | | | | | | |
| Voltage (2 phase) | volts rms | 26 | 26 | 26 | 26 | 26 |
| Frequency | Hz | 400 | 400 | 400 | 400 | 400 |
| Current - Start/phase | amps rms max | | | | | |
| - Run/phase | amps rms max | | | | | |
| Power (Total) - Start | watts max | 5 | 5 | 6 | 6 | 5 |
| - Run | watts max | 4 | 4 | 5 | 5 | 4 |
| Run-Up Time | sec max | 20 | 30 | 15 | 20 | 30 |
| PICKOFF: | | | | | | |
| Voltage | volts rms | 7 | 26 | 26 | 26 | 26 |
| Frequency | Hz | 1800 | 400 | 400 | 400 | 400 |
| Load | ohms, Pf max | 20K | 10K | 10K | 10K | |
| Scale Factor | mv/deg/sec | 33 | 80 | 100 | 30 | 83 |
| GYRO PERFORMANCE: | | | | | | |
| Threshold | deg/sec | 0.01 | 0.01 | 0.01 | 0.01 | 0.01 |
| Linearity | % max | 1 | 1 | 1 | 1 | 1 |
| Natural Frequency | Hz min | 50 | 25 | 31 | 50 | 35 |
| Damping Ratio | ----- | 0.3 to 1.0 | 0.4 to 1.2 | 0.4 to 1.0 | 0.4 to 1.0 | 0.3 to 1.5 |
| Acceleration Sensitivity | deg/sec/g max | 0.1 | 0.1 | 0.2 | 0.15 | 0.03 |
| Hysteresis | deg/sec max | 0.3 | 0.16 | 0.1 | 0.06 | 0.1 |
| Zero Offset | deg/sec max | 0.3 | 0.16 | 0.1 | 0.33 | 0.1 |
| ENVIRONMENTS: | | | | | | |
| Operating Temp. | °F | -65 to +212 | -65 to +160 | -25 to +160 | -31 to +150 | -10 to +212 |
| Shock, Duration | g-peak,msec | 20, 11 | 15, 11 | 500, 0.25 | 500, 1.5 | |
| Vibration 20-2000 Hz | g-peak | 20 | 10 | 5 | 15 | |
| Acceleration | g | 15 | 6 | 10 | 10 | 10 |



Rate Gyroscopes 475 Series

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|------------------------------|---------------|-------------|------------|-------------|-------------|-------------|
| USD Part Number | | 475225 | 475226 | 475227 | 475228 | 475229 |
| NSN | | | | | | |
| Honeywell Part Number | | | | | | |
| BAE Part Number | | 67680-301 | 67736-302 | 79022-303 | 67595-301 | 67603-301 |
| PARAMETER | UNIT | | | | | |
| Rate | ± deg/sec | 75 | 100 | 150 | 150 | 400 |
| SPINMOTOR: | | | | | | |
| Voltage (2 phase) | volts rms | 26 | 26 | 13.5 Square | 14.7 Square | 26 |
| Frequency | Hz | 400 | 400 | 800 | 1200 | 400 |
| Current - Start/phase | amps rms max | | | | | |
| - Run/phase | amps rms max | | | | | |
| Power (Total) - Start | watts max | 6 | 6 | 9 | 9 | 5 |
| - Run | watts max | 5 | 5 | 6 | 6 | 4 |
| Run-Up Time | sec max | 20 | 20 | 2.5 | 2 | 30 |
| PICKOFF: | | | | | | |
| Voltage | volts rms | 26 | 26 | 13.5 Square | 14.7 Square | 10 |
| Frequency | Hz | 400 | 400 | 800 | 1200 | 4500 |
| Load | ohms, Pf max | 200K | 16.5K | 10K | 50K | 10K |
| Scale Factor | mv/deg/sec | 70 | 70 | 35 | 10 | 10 |
| GYRO PERFORMANCE: | | | | | | |
| Threshold | deg/sec | 0.01 | 0.01 | 0.01 | 0.01 | 0.05 |
| Linearity | % max | 2 | 2 | 2 | 3 | 2 |
| Natural Frequency | Hz min | 30 | 40 | 38 | 54 | 100 |
| Damping Ratio | ----- | 0.4 to 1.0 | 0.4 to 0.8 | 0.4 to 0.8 | 0.4 to 1.2 | 0.3 to 1.5 |
| Acceleration Sensitivity | deg/sec/g max | 0.05 | 0.05 | 0.05 | 0.02 | 0.1 |
| Hysteresis | deg/sec max | 0.05 | 0.1 | 0.15 | 0.06 | 0.4 |
| Zero Offset | deg/sec max | 0.3 | 0.14 | 0.3 | 0.15 | 1 |
| ENVIRONMENTS: | | | | | | |
| Operating Temp. | °F | +32 to +100 | -4 to +160 | +32 to +160 | +32 to +190 | -65 to +212 |
| Shock, Duration | g-peak,msec | 20, 11 | 30, 11 | 40 | | 20, 11 |
| Vibration 20-2000 Hz | g-peak | 10 | 5 | 5 | 16 | 15 |
| Acceleration | g | | | 6 | 40 | 10 |



Rate Gyroscopes 475 Series

| USD Part Number | | 475230 | 475231 | 475232 | 475234 | 475235 |
|------------------------------|---------------|---------------|---------------|---------------|---------------|---------------|
| NSN | | 1015010766742 | 6615010714513 | 6615013223408 | 6615011435934 | 6615010546075 |
| Honeywell Part Number | | | | | | |
| BAE Part Number | | 13196 | 67699-302 | | 103003-005 | 12000 |
| PARAMETER | UNIT | | | | | |
| Rate | ± deg/sec | 60 | 300 | 100 | 100 | 50 |
| SPINMOTOR: | | | | | | |
| Voltage (2 phase) | volts rms | 26 | 26 | 28 | 26 | 15 |
| Frequency | Hz | 400 | 800 | 400 | 400 | 400 |
| Current - Start/phase | amps rms max | | | | | |
| - Run/phase | amps rms max | | | | 0.2 | |
| Power (Total) - Start | watts max | 6 | | 8 | | 7 |
| - Run | watts max | 5 | | 7.5 | 5 | 6 |
| Run-Up Time | sec max | 25 | 60 | 45 | 30 | 60 |
| PICKOFF: | | | | | | |
| Voltage | volts rms | 26 | 26 | 28 | 7 | 15 |
| Frequency | Hz | 400 | 800 | 400 | 1800 | 400 |
| Load | ohms, Pf max | 10K | 20K | | 20K | |
| Scale Factor | mv/deg/sec | 100 | 20 | 60 mvdc | 33 | 280 |
| GYRO PERFORMANCE: | | | | | | |
| Threshold | deg/sec | 0.03 | 0.01 | 0.01 | 0.05 | 0.01 |
| Linearity | % max | 2 | | 1 | 1 | 1 |
| Natural Frequency | Hz min | 31 | 47 | 40 | 50 | |
| Damping Ratio | ----- | 0.4 to 1.0 | 0.3 to 2.5 | 0.5 to 1.0 | 0.4 to 1.5 | 0.4 to 1.2 |
| Acceleration Sensitivity | deg/sec/g max | | 0.1 | 0.15 | 0.1 | 0.15 |
| Hysteresis | deg/sec max | 0.25 | 0.25 | 0.15 | 0.10 | 0.15 |
| Zero Offset | deg/sec max | | 0.25 | 0.35 | 0.30 | 0.15 |
| ENVIRONMENTS: | | | | | | |
| Operating Temp. | °F | -25 to +140 | -65 to +203 | -65 to +167 | -65 to +203 | -65 to +167 |
| Shock, Duration | g-peak,msec | 30, 11 | | 50, 11 | 25, 11 | |
| Vibration 20-2000 Hz | g-peak | 5 | 9 | 8 rms | 15 | |
| Acceleration | g | | | | 15 | |



Rate Gyroscopes 475 Series

| | | | | | | |
|------------------------------|---------------|-------------|------------|--|--|--|
| USD Part Number | | 475243 | 475244 | | | |
| NSN | | | | | | |
| Honeywell Part Number | | 7003315-901 | | | | |
| BAE Part Number | | | | | | |
| PARAMETER | UNIT | | | | | |
| Rate | ± deg/sec | 100 | 200 | | | |
| SPINMOTOR: | | | | | | |
| Voltage (2 phase) | volts rms | 26 | 26/52 | | | |
| Frequency | Hz | 400 | 400 | | | |
| Current - Start/phase | amps rms max | 200 | | | | |
| - Run/phase | amps rms max | 200 | | | | |
| Power (Total) - Start | watts max | 5 | 7 | | | |
| - Run | watts max | 3 | 5.7 | | | |
| Run-Up Time | sec max | 7 | 3 | | | |
| PICKOFF: | | | | | | |
| Voltage | volts rms | 10 | 26 | | | |
| Frequency | Hz | 4800 | 400 | | | |
| Load | ohms, Pf max | 90K | | | | |
| Scale Factor | mv/deg/sec | 72 | 19 | | | |
| GYRO PERFORMANCE: | | | | | | |
| Threshold | deg/sec | 0.01 | 0.01 | | | |
| Linearity | % max | | 2 | | | |
| Natural Frequency | Hz min | 60 | 60 | | | |
| Damping Ratio | ----- | 0.1 to 3.0 | 0.4 to 1.0 | | | |
| Acceleration Sensitivity | deg/sec/g max | 0.15 | 0.15 | | | |
| Hysteresis | deg/sec max | 0.12 | 0.3 | | | |
| Zero Offset | deg/sec max | 3 | 4 | | | |
| ENVIRONMENTS: | | | | | | |
| Operating Temp. | °F | -65 to 212 | -65 to 185 | | | |
| Shock, Duration | g-peak,msec | 350, 0.5 | 300, 6 | | | |
| Vibration 20-2000 Hz | g-peak | 1 rms | 30 rms | | | |
| Acceleration | g | 40 | 30 | | | |